Generalised reward generator $Z(\underline{s})$ for stochastic fluid models.

Aviva Samuelson^{1,3} with Małgorzata M. O'Reilly^{1,3} and Nigel G. Bean^{2,3}

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¹School of Physical Sciences, University of Tasmania. ²School of Mathematical Sciences, University of Adelaide.

³ARC Centre of Excellence for Mathematical and Statistical Frontiers.

 $\begin{array}{c} \mbox{Introduction}\\ \mbox{Generalised reward matrix} \ \mbox{Z}(\underline{s})\\ \mbox{Projections of } \ \mbox{Z}(\underline{s})\\ \mbox{New Riccati equation for } \Psi\\ \mbox{References} \end{array}$







- Projections of Z(<u>s</u>)
- 4 New Riccati equation for Ψ



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References

Motivating example



State i = 1, 2, 3 is a customer class.

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SFM definition

Continuous-time process $\{(\varphi(t), X(t)) : t \ge 0\}$ with

phase variable $\varphi(t)$ and unbounded level variable $X(t) \in \mathbb{R}$ such that

- phase process {φ(t) : t ≥ 0} is an irreducible CTMC with generator T and some finite-state space S
- the rate of change of X(t) at time t is $c_i = dX(t)/dt$ whenever $\varphi(t) = i$.

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Motivating example - continued

State space: $S = \{1, 2, 3\}$ where 1, 2, 3 are customer classes.

Fluid X(t): Amount of energy in the grid.

Rates c_i : $c_1 > 0$, $c_2 < 0$, and $c_3 = 0$.

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Sample path



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Some notation

$$S_{+} = \{i \in S : c_{i} > 0\}$$

 $S_{-} = \{i \in S : c_{i} < 0\}$
 $S_{0} = \{i \in S : c_{i} = 0\}$

$$\begin{aligned} \mathbf{T}_{+-} &= [\mathbf{T}_{ij}] \text{ for all } i \in \mathcal{S}_+, j \in \mathcal{S}_- \\ \mathbf{T}_{-+} &= [\mathbf{T}_{ij}] \text{ for all } i \in \mathcal{S}_-, j \in \mathcal{S}_+ \\ \mathbf{T}_{+0} &= [\mathbf{T}_{ij}] \text{ for all } i \in \mathcal{S}_+, j \in \mathcal{S}_0 \\ \text{etc.} \end{aligned}$$

$$oldsymbol{C}_+ = diag(c_i) ext{ for all } i \in \mathcal{S}_+$$

 $oldsymbol{C}_- = diag(|c_i|) ext{ for all } i \in \mathcal{S}_-$

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Motivation

In the literature so far, we have

- Laplace-Stieltjes Transforms (LSTs) of the time taken to complete a sample path in {(φ(t), X(t)) : t ≥ 0} using fluid generator Q(s)
- LSTs of the shift in X accumulated during a sample path in Y in {(φ(t), X(t), Y(t)) : t ≥ 0} using fluid generator W(s), where X(t) ∈ ℝ is unbounded.

Here, we wish to model, individually,

i-type rewards accumulated at rates *r_i* per unit time spent in *i* during a sample path in {(φ(t), X(t)) : t ≥ 0} where X(t) may be bounded/unbounded.

In-out fluid h(t)

In-out fluid:

$$h(t) = \int_{u=0}^{t} |c_{\varphi(u)}| du.$$

Time at which h(t) hits level y:

$$\omega(\mathbf{y}) = \inf\{t > \mathbf{0} : h(t) = \mathbf{y}\}.$$

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Evolution of in-out fluid h(t)



Assume *i*-type reward is generated at r_i per unit time spent in *i*.

Total *i*-type reward accumulated during [z, t] is defined as

$$W_i(z,t) = \int_{u=z}^t r_i I(\varphi(u) = i) du$$

where $I(\cdot)$ is an indicator function.

A set of total *i*-type rewards can be expressed as a vector $(W_1(z, t), \ldots, W_n(z, t))$.

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Phase *i* reward $W_i(0, t)$, for i = 1, 2, 3



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Laplace-Stieltjes transforms (LSTs) of interest

Let $\tilde{\Delta}^{Y}(\underline{\mathbf{s}})$ be a multi-dimensional LST matrix such that, for any y > 0, any vector $\mathbf{s} = [s_i]$, and any $i, j \in S_+ \cup S_-$,

$$[\tilde{\boldsymbol{\Delta}}^{\boldsymbol{y}}(\underline{\mathbf{s}})]_{ij} = E(e^{-(s_1W_1(0,\omega(\boldsymbol{y}))+\ldots+s_nW_n(0,\omega(\boldsymbol{y})))}I(\varphi(\omega(\boldsymbol{y}))=j) \mid \varphi(0)=i)$$

is the LST of the distribution of

 $(W_1(0,\omega(y)),\ldots,W_n(0,\omega(y)))$ and $\varphi(\omega(y))=j$,

given $\varphi(0) = i$.

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Theorem (2)

For any y > 0, $\tilde{\Delta}^{y}(\underline{s})$ exists and

$$\tilde{\boldsymbol{\Delta}}^{\boldsymbol{y}}(\underline{\mathbf{s}}) = \boldsymbol{e}^{\mathbf{Z}(\underline{\mathbf{s}})\boldsymbol{y}}.$$

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Generalised reward generator Z(s)

Assuming $\chi(\mathbf{T}_{00} - \mathbf{D}_0\mathbf{R}_0) < 0$, define

$$\mathbf{Z}(\underline{\mathbf{s}}) = \begin{bmatrix} \mathbf{Z}_{++}(\underline{\mathbf{s}}) & \mathbf{Z}_{+-}(\underline{\mathbf{s}}) \\ \mathbf{Z}_{-+}(\underline{\mathbf{s}}) & \mathbf{Z}_{--}(\underline{\mathbf{s}}) \end{bmatrix}$$

where $\underline{\mathbf{s}} = [s_i]$ and

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 $\begin{array}{c} \mbox{Introduction}\\ \mbox{Generalised reward matrix} {\bf Z}(\underline{s})\\ \mbox{Projections of } {\bf Z}(\underline{s})\\ \mbox{New Riccati equation for } {\bf \Psi}\\ \mbox{References} \end{array}$

Some more notation

Recall

$$S_+ = \{i \in S : c_i > 0\}$$

$$S_- = \{i \in S : c_i < 0\}$$

$$S_0 = \{i \in S : c_i = 0\}.$$

Let, for complex s_i ,

$$\mathbf{D}_{+} = diag(s_{i})$$
 for all $i \in S_{+}$
 $\mathbf{D}_{-} = diag(s_{i})$ for all $i \in S_{-}$
 $\mathbf{D}_{-} = diag(s_{i})$ for all $i \in S_{-}$

$$\mathbf{D}_0 = diag(s_i)$$
 for all $i \in S_0$

$$\begin{split} \mathbf{R}_{+} &= diag(r_i) \text{ for all } i \in \mathcal{S}_{+} \\ \mathbf{R}_{-} &= diag(r_i) \text{ for all } i \in \mathcal{S}_{-} \\ \mathbf{R}_{0} &= diag(r_i) \text{ for all } i \in \mathcal{S}_{0}. \end{split}$$

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Total reward W(z, t)

Total reward accumulated during [z, t] is defined as

$$W(z,t) = \sum_{i\in\mathcal{S}} W_i(z,t).$$

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Total reward W(0, t)



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Projections of $Z(\underline{s})$

- Replace rewards $W_i(z, t)$ with total reward W(z, t).
- Replace vector \underline{s} with scalar $s \in \mathbb{C}$.
- Derive corresponding fluid generators.

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Interpretation of $\mathbf{Q}(s)$

We want to know

$$E(e^{-(s\omega(y))}I(\varphi(\omega(y))=j) \mid \varphi(0)=i)$$

which is the LST of the distribution of

time $\omega(y)$, and $\varphi(\omega(y)) = j$,

given $\varphi(0) = i$.

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Projection from $Z(\underline{s})$ to Q(s)

Let

$$\begin{array}{rcl} \mathbf{R}_+ &=& \mathbf{I} \\ \mathbf{R}_- &=& \mathbf{I} \\ \mathbf{R}_0 &=& \mathbf{I} \end{array}$$

so that reward is $r_i = 1$ per unit of time spent in phase *i*.

Then the total reward is the total elapsed time,

$$W(z,t)=t-z.$$

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Fluid generator $\mathbf{Q}(s)$

The *i*, *j* th entry of the LST of the distribution is $[e^{\mathbf{Q}(s)y}]_{ij}$, where

$$\mathbf{Q}(s) = \left[egin{array}{cc} \mathbf{Q}_{++}(s) & \mathbf{Q}_{+-}(s) \ \mathbf{Q}_{-+}(s) & \mathbf{Q}_{--}(s) \end{array}
ight],$$

where

Interpretation of $\mathbf{Q}(s)$



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Interpretation of W(s)

We want to know

$$E(e^{-(sW(0,\omega(y)))}I(\varphi(\omega(y))=j) \mid \varphi(0)=i)$$

which is the LST of the distribution of the total shift in $Y(\cdot)$, accumulated at the time $\omega(y)$

when the *in-out fluid of the process* $X(\cdot)$ first reaches level *y*,

and $\varphi(\omega(y)) = j$ given $\varphi(0) = i$.

Projection from $Z(\underline{s})$ to W(s)

Let

$$\begin{array}{rcl} \mathbf{R}_+ &=& \mathbf{R}_+ \\ \mathbf{R}_- &=& \mathbf{R}_- \\ \mathbf{R}_0 &=& \mathbf{R}_0. \end{array}$$

Then the total reward is the total shift in the second (reward) fluid,

$$W(z,t)=Y(t)-Y(z).$$

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Fluid generator W(s) (most general projection)

The *i*, *j* th entry of the LST of the distribution is $[e^{W(s)y}]_{ij}$, where

$$\mathsf{W}(s) = \left[egin{array}{cc} \mathsf{W}_{++}(s) & \mathsf{W}_{+-}(s) \ \mathsf{W}_{-+}(s) & \mathsf{W}_{--}(s) \end{array}
ight],$$

with

$$\begin{split} \mathbf{W}_{++}(s) &= \mathbf{C}_{+}^{-1}[(\mathbf{T}_{++} - s\mathbf{R}_{+}) - \mathbf{T}_{+0}(\mathbf{T}_{00} - s\mathbf{R}_{0})^{-1}\mathbf{T}_{0+}] \\ \mathbf{W}_{--}(s) &= \mathbf{C}_{-}^{-1}[(\mathbf{T}_{--} - s\mathbf{R}_{-}) - \mathbf{T}_{-0}(\mathbf{T}_{00} - s\mathbf{R}_{0})^{-1}\mathbf{T}_{0-}] \\ \mathbf{W}_{+-}(s) &= \mathbf{C}_{+}^{-1}[\mathbf{T}_{+-} - \mathbf{T}_{+0}(\mathbf{T}_{00} - s\mathbf{R}_{0})^{-1}\mathbf{T}_{0-}] \\ \mathbf{W}_{-+}(s) &= \mathbf{C}_{-}^{-1}[\mathbf{T}_{-+} - \mathbf{T}_{-0}(\mathbf{T}_{00} - s\mathbf{R}_{0})^{-1}\mathbf{T}_{0+}]. \end{split}$$

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Interpretation of W(s)



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Interpretation of $Z^+(s)$

Define total upward shift

$$h_+(t) = \int_{u=0}^t |c_{\varphi(u)}| l(\varphi(u) \in \mathcal{S}_+) du.$$

We want to know

$$E(e^{-(sh_+(t))}I(\varphi(\omega(y))=j) \mid \varphi(0)=i)$$

is the LST of the distribution of

the total upward shift in X(t)

accumulated at time $\omega(y)$, and $\varphi(\omega(y)) = j$,

given $\varphi(0) = i$.

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Projection to track the total upward shift

Let

$$egin{array}{rcl} {f R}_+ &=& {f C}_+ \ {f R}_- &=& {f 0} \ {f R}_0 &=& {f 0}, \end{array}$$

so that the total reward is the total upward shift $h_+(t)$ in X(t)

$$W(0,t)=h_+(t).$$

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Z⁺(*s*)

The *i*, *j* th entry of the LST of the distribution is $[e^{\mathbf{Z}^+(s)y}]_{ij}$ where,

$${\sf Z}^+(s) \;\; = \;\; \left[egin{array}{ccc} {\sf Z}^+_{++}(s) & {\sf Z}^+_{+-}(s) \ {\sf Z}^+_{-+}(s) & {\sf Z}^+_{--}(s) \end{array}
ight]$$

where

$$\begin{aligned} \mathbf{Z}^{+}_{++}(s) &= \mathbf{C}^{-1}_{+}[\mathbf{T}_{++} - s\mathbf{C}_{+} - \mathbf{T}_{+0}(\mathbf{T}_{00})^{-1}\mathbf{T}_{0+}] \\ \mathbf{Z}^{+}_{--}(s) &= \mathbf{C}^{-1}_{-}[\mathbf{T}_{--} & -\mathbf{T}_{-0}(\mathbf{T}_{00})^{-1}\mathbf{T}_{0-}] \\ \mathbf{Z}^{+}_{+-}(s) &= \mathbf{C}^{-1}_{+}[\mathbf{T}_{+-} & -\mathbf{T}_{+0}(\mathbf{T}_{00})^{-1}\mathbf{T}_{0-}] \\ \mathbf{Z}^{+}_{-+}(s) &= \mathbf{C}^{-1}_{-}[\mathbf{T}_{-+} & -\mathbf{T}_{-0}(\mathbf{T}_{00})^{-1}\mathbf{T}_{0+}]. \end{aligned}$$

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Interpretation of $Z^+(s)$



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Density $\mathbf{f}_{y}(x)$

For $0 \le x \le y$, let $f_y(x)_{ij}$ be the inverse of the LST $[e^{\mathbf{Z}^+(s)y}]_{ij}$

so that

$$f_{\mathbf{y}}(\mathbf{x})_{ij} = \frac{d}{d\mathbf{x}} P(h_{+}(\omega(\mathbf{y})) \leq \mathbf{x}, \varphi(\omega(\mathbf{y})) = j | \mathbf{X}(0) = 0, \varphi(0) = i)$$

is the probability density that the total upward shift in $X(\cdot)$ accumulated at time $\omega(y)$ is $h_+(\omega(y)) = x$ and $\varphi(\omega(y)) = j$, given $\varphi(0) = i$.

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 $f_y(y/2)_{ij}$

is the probability density that the **total upward shift** in $X(\cdot)$ accumulated at time $\omega(y)$ is $h_+(\omega(y)) = y/2$ and $\varphi(\omega(y)) = j$, given $\varphi(0) = i$.

Total upward shift = Total downward shift.

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Consider $f_y(y/2)$



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Define M

Integrate $f_y(y/2)_{ij}$ over all possible y,

$$M_{ij}=\int_{y=0}^\infty f_y(y/2)_{ij}dy$$

which we interpret as

the expected number of visits to state (j, 0),

given that the process starts in state (i, 0),

for all $i, j \in S_+ \cup S_-$.

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Matrix M

Theorem (3)

We have

$$\begin{split} \mathbf{M} &= \left[\begin{array}{cc} \mathbf{M}_{++} & \mathbf{M}_{+-} \\ \mathbf{M}_{-+} & \mathbf{M}_{--} \end{array} \right] \\ &= \left[\begin{array}{cc} \mathbf{\Psi} \mathbf{M}_{-+} & (\mathbf{I} - \mathbf{\Psi} \mathbf{\Xi})^{-1} \mathbf{\Psi} \\ \mathbf{\Xi} (\mathbf{I} - \mathbf{\Psi} \mathbf{\Xi})^{-1} & \mathbf{\Xi} \mathbf{M}_{+-} \end{array} \right] \end{split}$$

where Ψ,Ξ are respective minimum nonnegative solutions to

$$\begin{aligned} \mathbf{Q}_{+-} + \mathbf{Q}_{++} \Psi + \Psi \mathbf{Q}_{--} + \Psi \mathbf{Q}_{-+} \Psi &= \mathbf{0}, \\ \mathbf{Q}_{-+} + \mathbf{Q}_{--} \Xi + \Xi \mathbf{Q}_{++} + \Xi \mathbf{Q}_{+-} \Xi &= \mathbf{0}. \end{aligned}$$

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Corollary (1)

Ψ is a solution to the Riccati equation

 $M_{+-}=\Psi+\Psi M_{-+}\Psi.$

Corollary (2)

 Ψ can be explicitly written as

$$\Psi = \mathbf{M}_{+-}(\mathbf{I} + \mathbf{M}_{--})^{-1}$$

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• Numerical examples.

• Algorithm for computing **M** efficiently.

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- Constructed generalised reward generator Z(<u>s</u>)
- considered various projections
- concentrated on Z⁺(s)
 - inverted its corresponding LST
 - integrated over all y to get M
 - and created an explicit equation for Ψ .

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Thank you for listening

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Generators derived from $Z(\underline{s})$

$$\begin{array}{rcl} J_1(\underline{s}) & = & Z_{--}(\underline{s}) + Z_{-+}(\underline{s}) \Psi(\underline{s}) \\ J_2(\underline{s}) & = & Z_{++}(\underline{s}) + Z_{+-}(\underline{s}) \Xi(\underline{s}) \end{array}$$

$$\begin{array}{lll} \mathsf{J}_3(\underline{s}) &=& \mathsf{Z}_{++}(\underline{s}) + \Psi(\underline{s})\mathsf{Z}_{-+}(\underline{s}) \\ \mathsf{J}_4(\underline{s}) &=& \mathsf{Z}_{--}(\underline{s}) + \Xi(\underline{s})\mathsf{Z}_{+-}(\underline{s}) \end{array}$$

$$\begin{array}{rcl} \mathsf{J}_5(\underline{\mathbf{s}}) &=& \mathsf{Z}_{++}(\underline{\mathbf{s}}) + \mathsf{Z}_{+-}(\underline{\mathbf{s}})\mathsf{H}^{(b,b)}(\underline{\mathbf{0}}) \\ \mathsf{J}_6(\underline{\mathbf{s}}) &=& \mathsf{Z}_{--}(\underline{\mathbf{s}}) + \mathsf{Z}_{-+}(\underline{\mathbf{s}})\mathsf{G}^{(0,b)}(\underline{\mathbf{0}}) \end{array}$$

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