

Monotonicity, Convexity and Comparability of Some Functions Associated with Block-Monotone Markov Chains and Their Applications to Queueing Systems

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1. Introduction

- **Queueing Systems & Univariate Markov chains**
 - Research in this area started in 1950's
 - Classical queues: $M/M/1$, $M/G/1$, $GI/M/1$, $GI/Geo/1$,...
- **Imbeeded Markov chain:** (e.g., Kendall 1951,1953), Hunter (1983), Tian and Zhang (2002))
- **Stochastic comparison methods:** (e.g.,Stoyan (1983))
- **Monotonicity and convexity of functions *w.r.t.* univariate Markov chains**(Yu, He and Zhang (2006))
- **Question:** Whether above results may be extended to **bivariate Markov chains?**

1. Introduction (continued)

- **Bivariate Markov chains with block-structured transition matrices (e.g., QBD)**
 - Research in this area started in 1980's.
 - Continuous-time queues: $GI/PH/1$, $PH/G/1$, $MAP/PH/1$, ...
 - Discrete-time queues: $GI/Geo/1$, $GI/G/1$, ...
 - Methods: Matrix-analytic method (MAM) vs. block-monotone Markov chain
- **MAM:** (Neuts (1981,1989), Gibson and Seneta (1987), Zhao, Li and Alfa (2000); Tweedie(1998), Liu (2010), He(2014), Alfa (2016), etc.)

1. Introduction (continued)

- **Block-monotone Markov chain approach**
 - First introduced the stochastic vectors based on F-orderings (Li and Shaked (1994))
 - Defined the block-increasing order, and proved the stationary distributions of its truncations converge to that of the original Markov chain with monotone transition matrix (Li and Zhao (2000))
 - Provided error bounds for augmented truncations of discrete-time block-monotone Markov chains under geometric drift conditions (Masuyama (2015)).
 - Continuous-time block-monotone Markov chain (Masuyama (2016)).

2. Block-Monotonicity of Probability Vectors and Stochastic Matrices

- **Definition:Block Stochastic orders**

- $\mathbf{a}=(\mathbf{a}_0, \mathbf{a}_1, \mathbf{a}_2, \dots), \mathbf{b}=(\mathbf{b}_0, \mathbf{b}_1, \mathbf{b}_2, \dots)$, where $\mathbf{a}_n=(a_n(1), a_n(2), \dots, a_n(m)), \mathbf{b}_n=(b_n(1), b_n(2), \dots, b_n(m))$.

$\mathbf{a} \leq_{m-s-st} \mathbf{b}$, if $\mathbf{a} E_m^s \leq_{el} \mathbf{b} E_m^s$, for $s = 1, 2$

where

$$E_m = \begin{pmatrix} I_m & O & O & O & \dots \\ I_m & I_m & O & O & \dots \\ I_m & I_m & I_m & O & \dots \\ I_m & I_m & I_m & I_m & \ddots \\ \vdots & \vdots & \vdots & \ddots & \ddots \end{pmatrix}, E_m^2 = \begin{pmatrix} I_m & O & O & O & \dots \\ 2I_m & I_m & O & O & \dots \\ 3I_m & 2I_m & I_m & O & \dots \\ 4I_m & 3I_m & 2I_m & I_m & \ddots \\ \vdots & \vdots & \vdots & \ddots & \ddots \end{pmatrix} \quad (1)$$

Note: For $s = 1$, Li and Zhao (2000) defined the order \leq_{m-1-st}

2. Block-Monotonicity of Probability Vectors and Stochastic Matrices(continued)

Example 1.

$$1) \mathbf{a}_0 = (0.3, 0.2), \mathbf{a}_1 = (0.3, 0.2),$$

$$\mathbf{b}_0 = (0.2, 0.2), \mathbf{b}_1 = (0.4, 0.2), \text{ then } \mathbf{a} \leq_{m-1-st} \mathbf{b}.$$

$$2) \mathbf{a} = (\mathbf{a}_0, \mathbf{a}_1, \mathbf{a}_2, \dots), \mathbf{b} = (\mathbf{a}_0 + \mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3, \dots), \text{ then } \mathbf{a} \leq_{m-1-st} \mathbf{b}$$

Example 2.

$$\mathbf{a}_0 = (0.25, 0.25), \mathbf{a}_1 = (0.15, 0.15), \mathbf{a}_2 = (0.1, 0.1),$$

$$\mathbf{b}_0 = (0.21, 0.21), \mathbf{b}_1 = (0.17, 0.17), \mathbf{b}_3 = (0.12, 0.12),$$

$$\text{then } \mathbf{a} \leq_{m-2-st} \mathbf{b}.$$

2. Block-Monotonicity of Probability Vectors and Stochastic Matrices(continued)

- **Definition: Block-Monotone Stochastic Matrices**

Let $\mathbf{P} = (A_{k,l})$, $A_{k,l} = (A_{k,l}(i,j))$, $i,j=1,2, \dots, m$ $k,l=0,1,2, \dots$

$$\mathbf{P} \in M_{m-s-st} \quad , \text{ if } \mathbf{E}_m^{-1} \mathbf{P} \mathbf{E}_m^s \geq_{el} \mathbf{O} \quad \text{for } s = 1, 2.$$

- For $n = 1$, Definition of $\mathbf{P} \in M_{m-1-st}$ (Masuyama (2015))
- For $n = 1$, $\mathbf{P} \in M_{m-1-st} \iff \mathbf{a} \leq_{m-1-st} \mathbf{b}$ implies $\mathbf{a} \mathbf{P} \leq_{m-1-st} \mathbf{b} \mathbf{P}$ (Li and Zhao (2000))

2. Block-Monotonicity of Probability Vectors and Stochastic Matrices(continued)

- Example 3 :QBD**

$$P = \begin{pmatrix} B & C & O & O & \dots \\ F & A_1 & A_0 & O & \dots \\ O & A_2 & A_1 & A_0 & \dots \\ O & O & A_2 & A_1 & \ddots \\ \vdots & \vdots & \vdots & \ddots & \ddots \end{pmatrix}$$

i)If $F \leq_{el} B$, $F \leq_{el} A_2$, and $B + C \leq_{el} F + A_1 + A_0$,

then $P \in M_{m-1-st}$

ii)If $F \leq_{el} B + A_0$, $F \leq_{el} 2A_2 + A_1 + A_0$,and

$B + 2C \leq_{el} F + 2A_1 + 3A_0$,then $P \in M_{m-2-st}$

- Example 4. QBD for $GI/Geo/1$ queue (Alfa 2016)**

$$B = \begin{pmatrix} 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \ddots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}$$

$$C = \begin{pmatrix} g_1 & g_2 & g_3 & \dots & g_m \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \ddots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix}$$

$$F = A_2 = \mu B$$

$$A_1 = \bar{\mu}B + \mu C$$

$$A_0 = \bar{\mu}C$$

Then $P \in M_{m-1-st}$, $P \in M_{m-2-st}$.

2. Block-Monotonicity of Probability Vectors and Stochastic Matrices(continued)

- **Property 1:** Suppose that $P \in M_{m-s-st}$, $s=1,2$, then
 - $a \leq_{m-s-st} b \Rightarrow aP^n \leq_{m-s-st} bP^n$ for $n=1,2, \dots$
 - $a \leq_{m-s-st} aP \Rightarrow aP^n \leq_{m-s-st} aP^{n+1}$ for $n=1,2, \dots$
 - $aP \leq_{m-s-st} a \Rightarrow aP^{n+1} \leq_{m-s-st} aP^n$ for $n=1,2, \dots$

3. Block-Monotone Markov Chains(continued)

- **Theorem 1:** For a DTMC $Z=\{Z_n, n \in \mathbb{N}_0\}$ with transition matrix P having block size m and initial distribution ν . Assume that $\mathbf{E}_\nu[f(Z_n)] = \nu P^n f^T < \infty$
 - 1) If **Condition I_{m-s-st} , II_{m-s-st}** and **III_{m-s-st}** in Eq.(2) hold, then $\mathbf{E}_\nu[f(Z_n)]$ is increasing concave in n for $n=0,1,2,\dots$ and $s=1,2$.
 - 2) If **Condition I_{m-s-st} , II'_{m-s-st}** and **III_{m-s-st}** in Eq.(2) hold, then $\mathbf{E}_\nu[f(Z_n)]$ is decreasing convex in n for $n=0,1,2,\dots$ and $s=1,2$.

3. Block-Monotone Markov Chains(continued)

For $s = 1, 2,$

Condition I _{$m-s-st$} : $P \in M_{m-s-st}$

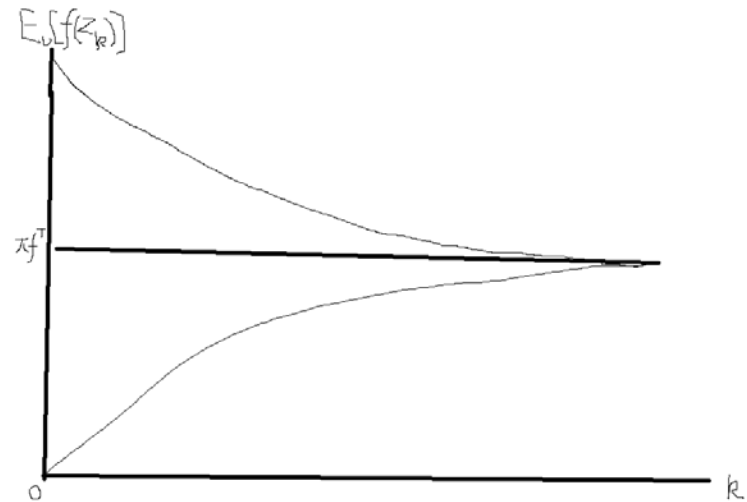
Condition II _{$m-s-st$} : $v \leq_{m-s-st} vP$

Condition II' _{$m-s-st$} : $vP \leq_{m-s-st} v$ (2)

Condition III _{$m-1-st$} : h_f^T is decreasing w.r.t. orders \leq_{m-s-st}

where

$$h_f^T = Pf^T - f^T$$



3. Block-Monotone Markov Chains(continued)

- Theorem 2:** For two DTMCs $Z = \{Z_n, n \in \mathbb{N}_0\}$ and $\tilde{Z} = \{\tilde{Z}_n, n \in \mathbb{N}_0\}$ with the same state space and initial distribution ν , If their transition matrices \mathbf{P} and $\tilde{\mathbf{P}}$ satisfy: $\mathbf{P} \leq_{m-s-st} \tilde{\mathbf{P}}$, and either $\mathbf{P} \in M_{m-s-st}$ or $\tilde{\mathbf{P}} \in M_{m-s-st}$, then $\mathbf{E}_\nu[f(Z_n)] \leq \mathbf{E}_\nu[f(\tilde{Z}_n)]$ for $n=0,1,2,\dots$, and $s=1,2$.
- Proof based on Property 2:**
- Property 2:** Suppose $\mathbf{P} \leq_{m-s-st} \tilde{\mathbf{P}}$ (i.e., $\mathbf{P}\mathbf{E}_m^s \leq_{m-s-st} \tilde{\mathbf{P}}\mathbf{E}_m^s$) and either $\mathbf{P} \in M_{m-s-st}$ or $\tilde{\mathbf{P}} \in M_{m-s-st}$, then $\mathbf{P}^n \leq_{m-s-st} \tilde{\mathbf{P}}^n$

Note: Li and Zhao (2000) gave result in property 2 for $s=1$

4. Application to the *GI/Geo/1* Queue

- There is a single server. Service times follow the geometric distribution with parameter μ , $0 < \mu < 1$
- Service discipline: first-come-first-served (FCFS).
- Inter-arrival times are follow a general distributions, $\mathbf{g}=(g_1, g_2, \dots, g_m)$, $m < \infty$, and with DPH representation (β, B) of order m , where $\beta=(g_1, g_2, \dots, g_m)$, B is given in Eq. (4).

4. Application to the *GI/Geo/1* Queue (continued)

- DTMC $\mathbf{Z} = \{(I_n, J_n), n=0,1,2,\dots\}$
- I_n : the number of customers in the system at time n
- J_n : the remaining inter-arrival time at time n
- The transition matrix P given by

$$P = \begin{pmatrix} B & C & O & O & \dots \\ A_2 & A_1 & A_0 & O & \dots \\ O & A_2 & A_1 & A_0 & \dots \\ O & O & A_2 & A_1 & \ddots \\ \vdots & \vdots & \vdots & \ddots & \ddots \end{pmatrix} \quad (3)$$

4. Application to the *GI/Geo/1* Queue (continued)

where

$$B = \begin{pmatrix} 0 & 0 & 0 & \cdots & 0 \\ 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \ddots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \end{pmatrix} \quad (4)$$

$$C = \begin{pmatrix} g_1 & g_2 & g_3 & \cdots & g_m \\ 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & \ddots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 0 \end{pmatrix} \quad (5)$$

$$A_2 = \mu B, \quad A_1 = \bar{\mu} B + \mu C, \quad A_0 = \bar{\mu} C \quad (6)$$

4. Application to the *GI/Geo/1* Queue (continued)

For the *GI/Geo/1* Queue

- **Corollary 1:**

1) If **Condition** I_{m-1-st} in Eq.(7), II_{m-1-st} in Eq.(8) and II_{m-1-st} in Eq.(9) hold, then $E_v[f(Z_n)]$ is increasing concave in n .

2) If Conditions I_{m-1-st} in Eq.(7), II'_{m-1-st} in Eq.(8') and II_{m-1-st} in Eq.(9) hold, then $E_v[f(Z_n)]$ is decreasing convex in n .

4. Application to the *GI/Geo/1* Queue (continued)

Condition I_{m-1-st} : $0 < \mu < 1$ (7)

Condition II_{m-1-st} : For $j=1,2,\dots, m-1$,

$$\bar{g}_j \sum_{i=0}^k v_i(j) + \bar{\mu} g_j v_k(j) - \left(\sum_{i=0}^k v_i(j+1) + \mu v_{k+1}(j+1) \right) \geq 0 \quad (8)$$

$$v_0(j) - v_0(j+1) - \mu v_0(j+1) \geq 0$$

$$\sum_{i=0}^k v_i(m) - g_m \left(\sum_{i=0}^{k-1} v_i(m) + \mu v_k(m) \right) \geq 0$$

Condition II'_{m-1-st} : For $j=1,2,\dots, m-1$,

$$\bar{g}_j \sum_{i=0}^k v_i(j) + \bar{\mu} g_j v_k(j) - \left(\sum_{i=0}^k v_i(j+1) + \mu v_{k+1}(j+1) \right) \leq 0$$

$$v_0(j) - v_0(j+1) - \mu v_0(j+1) \leq 0$$

$$\sum_{i=0}^k v_i(m) - g_m \left(\sum_{i=0}^{k-1} v_i(m) + \mu v_k(m) \right) \leq 0 \quad (8')$$

4. Application to the *GI/Geo/1* Queue (continued)

*Condition III*_{*m-1-st*}:

$$\Delta f_{k+1}(1) \geq \mu \sum_{j=1}^m g_j [\Delta f_{k+1}(j) - \Delta f_{k+2}(j)] + \sum_{j=1}^m g_j \Delta f_{k+2}(j) \quad \text{for } k=1,2,\dots$$

$$\Delta f_{k+1}(j+1) - \Delta f_{k+1}(j) \geq \mu [\Delta f_k(j) - \Delta f_{k+1}(j)] \quad (9)$$

$$\begin{aligned} \Delta f_1(1) &\geq \bar{\mu} \sum_{j=1}^m g_j \Delta f_1(j) && \text{for } k=1,2,\dots, j=1,2,\dots, m-1. \\ \Delta f_1(j+1) &\geq \bar{\mu} \Delta f_1(j) && \text{for } j=1,2,\dots, m-1. \end{aligned}$$

- For example, taking $f_n(j)=n$ for $n=0,1,2,\dots, j=1,2,\dots, m$. then the function $f=(f_0, f_1, f_2, \dots)$ satisfies *Condition III*_{*m-1-st*}

4. Application to the *GI/Geo/1* Queue (continued)

- **Corollary 2:** For two *GI(n)/Geo(n)/1* queues

-- service rates μ_n and $\tilde{\mu}_n$

-- inter-arrival times $g_n = (g_n(1), g_n(m), \dots, g_n(m))$

$\tilde{g}_n = (\tilde{g}_n(1), \tilde{g}_n(m), \dots, \tilde{g}_n(m))$

Suppose that $\mu_{n+1} \leq g_n(j) / g_{n+1}(j)$, $\mu_n \geq \tilde{\mu}_n$

and $g_n(j) \leq \tilde{g}_n(j)$ for $n=0,1,2,\dots$, $j=1,2,\dots, m$,

then $\mathbf{E}_v[f(Z_n)] \leq \mathbf{E}_v[f(\tilde{Z}_n)]$ for all $n=0,1,2,\dots$,

5. Numerical Examples

- Consider the *GI/Geo/1* Queue system with $g = (0.5, 0.5)$, $\lambda = 2/3$, $\mathbf{v} = (v_0, 0, 0, \dots)$, $v_0 = (3/4, 1/4)$, $f_n(j)=n$, $\mu = \mathbf{0.8}$,

$$B = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 0.5 & 0.5 \\ 0 & 0 \end{pmatrix};$$

$$A_2 = \begin{pmatrix} 0 & 0 \\ 0.8 & 0 \end{pmatrix}, \quad A_1 = \begin{pmatrix} 0.4 & 0.4 \\ 0.2 & 0 \end{pmatrix}, \quad A_0 = \begin{pmatrix} 0.1 & 0.1 \\ 0 & 0 \end{pmatrix}.$$

- Consider another *GI/Geo/1* Queue system with $g = (0.5, 0.5)$, $\lambda = 2/3$, $\mathbf{v} = (v_0, 0, 0, \dots)$, $v_0 = (3/4, 1/4)$, $f_n(j)=n$, $\mu' = \mathbf{0.75}$.

n	0	1	2	3	4	5	6
$E_v[f(Z_n)]$	0	0.7500	0.7750	0.7950	0.8150	0.8350	0.8550
$E_v[f(Z'_n)]$	0	0.7500	0.8125	0.8325	0.8525	0.8725	0.8925

6. Conclusion

- Sufficient conditions to assure the monotonicity and convexity of function for block-monotone Markov chain can be obtained.
- Our approach can be used to analyze those complex queueing systems, e.g.,
 - *GI/G/1 queue*, (Alfa 2016 Section 5.12)
 - *GI(n)/G(n)/1 queue*
 - *GI/Geo/1 queue with server vacations*

Thank you very much!