

M/M/1/N queues with energy required service and phase type vacation time

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Nikhil.A.P ^a, Miklos Telek ^{b,c}, and Deepak.T.G ^a

^a Indian Institute of Space Science and Technology,
Department of Mathematics, Thiruvananthapuram, India,

^bMTA-BME Information Systems Research Group, Budapest, Hungary

^cBudapest University of Technology and Economics, Department of
Networked Systems and Services, Budapest, Hungary



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So in this model, apart from fluid level and state of the underlying Markov process as state variables , we need to take the number of customers in the system also as state variable. This is the basic difference between a usual fluid flow model and the proposed model.



Literature Review

- Ramaswami (1999) used renewal argument for analysing fluid flow models, which led to solution in matrix-exponential form.
- Da Silva Soares and Latouche (2006) used matrix analytic methods and obtained a representation of fluid model in terms of a QBD.
- Computational approach to find various performance measures of fluid models have been improved by N. Bean et al (2005).
- Horvath and Telek [2015], and Saffer and Telek [2016] studied fluid vacation models in detail under exhaustive disciplines. They followed a new methodology based on the matrix analytic analysis of the Markov fluid queues.
- The detailed analysis of our proposed model is very much inspired by the same in Horvath and Telek [2015] and Saffer and Telek [2016] for fluid vacation models.



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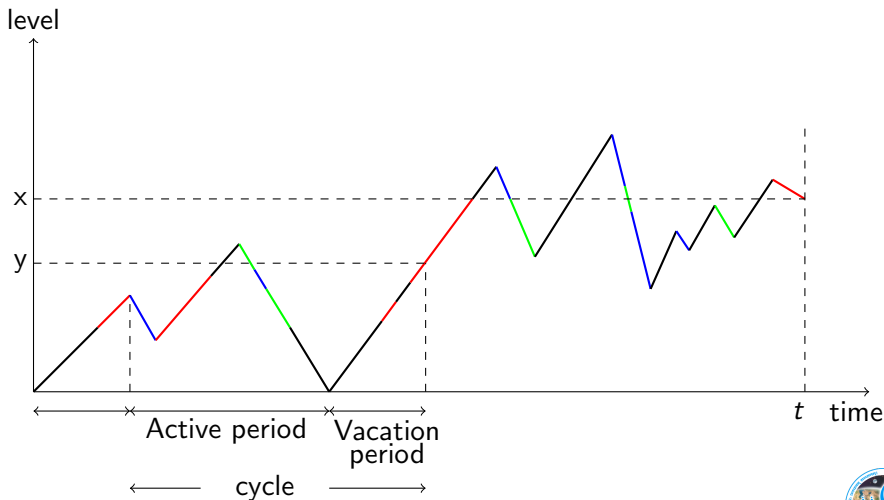
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Possible evolution of the fluid level



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Now we partition S into two sets namely,
 $S_+ = \{i \in S, r_i > 0\}$ and $S_- = \{i \in S, r_i < 0\}$ according to the signs
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Then generator matrix Q and fluid rate matrix R of $(Y(t), \vartheta(t))$ are given by

$$Q = \begin{bmatrix} Q_v \oplus A & I \otimes a \\ 0 & Q_s \end{bmatrix}, \quad R = \begin{bmatrix} R_{\varphi(t)} \otimes I_N \otimes I_{n_{PH}} & 0 \\ 0 & R_{\varphi(t)} \otimes I_{(N+1)} - I \otimes D_{N(t)} \end{bmatrix}$$

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where S_{PH} stands for the set of transient states of PH vacation variable.



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$$Q = \begin{bmatrix} Q_v \oplus A & I \otimes a \\ 0 & Q_s \end{bmatrix}, \quad R = \begin{bmatrix} R_{\varphi(t)} \otimes I_N \otimes I_{n_{PH}} & 0 \\ 0 & R_{\varphi(t)} \otimes I_{(N+1)} - I \otimes D_{N(t)} \end{bmatrix}$$

where

$$D_{N(t)} = \text{diag}(d_n) \text{ is of order } N+1 \text{ with } d_n = \begin{cases} 0 & \text{if } n = 1 \\ d & \text{if } 1 < n \leq N+1 \end{cases}$$

Now let us arrange the state space of the process $(Y(t), \vartheta(t))$ as

$\Theta = \{S_{\varphi(t)}^+ \times S_N \times S_{PH}, S_{\varphi(t)}^- \times S_N \times S_{PH}, S_{\varphi(t)} \times \{0\}, S_{\varphi(t)}^+ \times S_N, S_{\varphi(t)}^- \times S_N\}$
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Analysis

Under this transformation, the matrices R and Q assume the forms

$$\mathbf{C} = \mathbf{PRP}^{-1} = \left[\begin{array}{c|c} \mathbf{C}^+ & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{C}^- \end{array} \right] =$$

$$\left[\begin{array}{cccc|c} \mathbf{R}_{\varphi(t)}^+ \otimes \mathbf{I}_N \otimes \mathbf{I}_{n_{PH}} & \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{R}_{\varphi(t)}^- \otimes \mathbf{I}_N \otimes \mathbf{I}_{n_{PH}} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{R}_{\varphi(t)} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & (\mathbf{R}_{\varphi(t)}^+ - d\mathbf{I}) \otimes \mathbf{I}_N & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} & (\mathbf{R}_{\varphi(t)}^- - d\mathbf{I}) \otimes \mathbf{I}_N \end{array} \right]$$

and

$$\mathbf{T} = \mathbf{PQP}^{-1} = \left[\begin{array}{c|c} \mathbf{T}^{++} & \mathbf{T}^{+-} \\ \hline \mathbf{T}^{-+} & \mathbf{T}^{--} \end{array} \right].$$



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This way the first four matrix blocks of \mathbf{C} and \mathbf{T} are associated with the states in Θ^+ and the last one with the states in Θ^- . Consequently, $|\Theta^+| = |S_{\varphi(t)}^+| \cdot N \cdot n_{PH} + |S_{\varphi(t)}^-| \cdot N \cdot n_{PH} + |S_{\varphi(t)}| + |S_{\varphi(t)}^+| \cdot N$ and



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$$|\Theta^-| = |S_{\varphi(t)}^-| \cdot N.$$



Stability Condition

Let $\bar{\pi}_{\varphi(t)}$ and $\bar{\pi}_{N(t)}$ be the steady state probability vectors of the Markov processes $\varphi(t)$ and $N(t)$ respectively. That is,

$$\bar{\pi}_{\varphi(t)} \mathbf{Q}_{\varphi(t)} = \mathbf{0} \quad , \quad \bar{\pi}_{\varphi(t)} \mathbf{e} = 1$$

and

$$\bar{\pi}_{N(t)} \mathbf{Q}_{N(t)}^S = \mathbf{0} \quad , \quad \bar{\pi}_{N(t)} \mathbf{e} = 1.$$

Mean fluid inflow rate

$$\lambda_{in} = \bar{\pi}_{\varphi(t)} \mathbf{R}_{\varphi(t)} \mathbf{e}$$

Effective mean fluid outflow rate

$$d_{out} = \bar{\pi}_{N(t)} \mathbf{D}_{N(t)} \mathbf{e}.$$

Stability condition: $\rho = \frac{\lambda_{in}}{d_{out}} < 1.$



Mean cycle length and fluid density in steady state regime

Theorem 1

Stationary distribution of $Y(t) = (\varphi(t), N(t))$ at a vacation start epoch is given by $\mathbf{m} = [\mathbf{m}^+, \mathbf{m}^-] = [\mathbf{0}, \mathbf{m}^-]$ where \mathbf{m}^- satisfies

$$\mathbf{m}^- = \mathbf{m}^- \left[\mathbf{0} \quad \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha \quad \mathbf{0} \quad \mathbf{0} \right] \Psi$$

with normalizing condition $\mathbf{m}^- \mathbf{e}_{|S_{\varphi(t)}^-| \cdot N} = 1$.

Here matrix $\Psi = (\Psi_{ij})$ is given by

$$\Psi_{ij} = \Pr[Z(\gamma) = j \mid X(0) = 0, Z(0) = i], \quad \text{for } i \in \Theta^+, j \in \Theta^-$$

where $\gamma = \inf\{t > 0; X(t) = 0\}$ is the first passage time to level 0 and Ψ is the solution of the Ricatti equation

$$\Psi (-\mathbf{C}^-)^{-1} \mathbf{T}_{-+} \Psi + \Psi (-\mathbf{C}^-)^{-1} \mathbf{T}_{--} + (\mathbf{C}^+)^{-1} \mathbf{T}_{++} \Psi + (\mathbf{C}^+)^{-1} \mathbf{T}_{+-}$$



Theorem 2

The steady state mean cycle time \mathbf{c} and the vector density $\mathbf{q}(\cdot)$ of fluid level at an arbitrary epoch are given by

$$\mathbf{c} = \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} (-\mathbf{K})^{-1} \begin{bmatrix} \mathbf{I}_{|\Theta^+|} & \Psi \end{bmatrix} |\mathbf{C}|^{-1} \mathbf{e}_{|\Theta|} \text{ and}$$

$$\mathbf{q}(x) = \frac{1}{c} \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} e^{\mathbf{K}x} \begin{bmatrix} \mathbf{I}_{|\Theta^+|} & \Psi \end{bmatrix} |\mathbf{C}|^{-1} \mathbf{P} \begin{bmatrix} \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{e}_N \otimes \mathbf{e}_{n_{PH}} \\ \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{e}_{N+1} \end{bmatrix}.$$



Proof:

$$\begin{aligned}c &= \lim_{\ell \rightarrow \infty} \sum_{i \in \Theta} E(\gamma \mid Z(t^m(\ell)) = i, X(t^m(\ell)) = 0) \Pr(Z(t^m(\ell)) = i) \\&= \lim_{\ell \rightarrow \infty} \sum_{i \in \Theta} \int_{t=t^m(\ell)}^{\infty} \Pr(\gamma > t - t^m(\ell) \mid Z(t^m(\ell)) = i, X(t^m(\ell)) = 0) dt \Pr(Z(t^m(\ell)) = i) \\&= \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} \int_{x=0}^{\infty} \mathbf{G}(x) \mathbf{e} \\&= \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} (-\mathbf{K})^{-1} \begin{bmatrix} \mathbf{I}_{|\Theta^+|} & \Psi \end{bmatrix} |\mathbf{C}|^{-1} \mathbf{e}_{|\Theta|}.\end{aligned}$$

Here $\mathbf{G}(x) = [\mathbf{G}_{i,j}(x)]$, where

$$\mathbf{G}_{i,j}(x) = \frac{d}{dx} \int_{t=0}^{\infty} \Pr(\gamma > t, Z(t) = j, X(t) < x \mid Z(0) = i, X(0) = 0) dt,$$

of size $|\Theta^+| \times |\Theta|$ can be computed as

$$\mathbf{G}(x) = e^{\mathbf{K}x} \begin{bmatrix} \mathbf{I} & \Psi \end{bmatrix} |\mathbf{C}|^{-1},$$

where \mathbf{K} , of size $|\Theta^+| \times |\Theta^+|$, is given by $\mathbf{K} = \Psi (-\mathbf{C}^-)^{-1} \mathbf{T}_{-+} + (\mathbf{C}^+)^{-1} \mathbf{T}_{++}$



The vector density of fluid level at arbitrary epoch is the normalized fluid level during the stationary cycle. So

$$\mathbf{q}(x) = \frac{1}{c} \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} \mathbf{G}(x) \begin{bmatrix} \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{e}_N \otimes \mathbf{e}_{n_{PH}} \\ \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{e}_{N+1} \end{bmatrix}$$

Theorem 3

The vector Laplace transform of the stationary fluid level,

$$\mathbf{q}^*(v) = \frac{1}{c} \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} (v \mathbf{I}_{|\Theta^+|} - \mathbf{K})^{-1} \\ \begin{bmatrix} \mathbf{I}_{|\Theta^+|} & \Psi \end{bmatrix} |\mathbf{C}|^{-1} \mathbf{P} \begin{bmatrix} \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{e}_N \otimes \mathbf{e}_{n_{PH}} \\ \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{e}_{N+1} \end{bmatrix}.$$



Theorem 4

The n^{th} order stationary moment of the fluid level is given by

$$\mathbf{q}^{(n)} = \frac{n!}{c} \mathbf{m}^{-1} \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} (-\mathbf{K})^{-1-n} \\ \begin{bmatrix} \mathbf{I}_{|\Theta^+|} & \Psi \end{bmatrix} |\mathbf{C}|^{-1} \mathbf{P} \begin{bmatrix} \mathbf{I}_{|S_{\varphi(t)}|} \otimes \mathbf{e}_N \otimes \mathbf{e}_{n_{PH}} \\ \mathbf{I}_{|S_{\varphi(t)}|} \otimes \mathbf{e}_{N+1} \end{bmatrix}$$

In particular, the stationary mean fluid level

$$\mathbf{q}^{(1)} = \frac{1}{c} m^{-1} \mathbf{W} (-\mathbf{K})^{-2} \begin{bmatrix} \mathbf{I}_{|\Theta^+|} & \Psi \end{bmatrix} |\mathbf{C}|^{-1} \mathbf{M}$$

where

$$\mathbf{W} = \begin{bmatrix} \mathbf{0} & \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha & \mathbf{0} & \mathbf{0} \end{bmatrix} \text{ and } \mathbf{M} = \mathbf{P} \begin{bmatrix} \mathbf{I}_{|S_{\varphi(t)}|} \otimes \mathbf{e}_N \otimes \mathbf{e}_{n_{PH}} \\ \mathbf{I}_{|S_{\varphi(t)}|} \otimes \mathbf{e}_{N+1} \end{bmatrix}$$

Queue size distribution

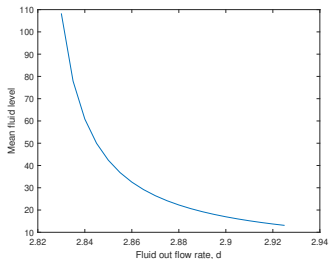
Theorem 5

The steady state distribution of queue size $p = (p_0, p_1, p_2, \dots, p_N)$, where $p_n = \lim_{t \rightarrow \infty} p_n(t) = \lim_{t \rightarrow \infty} \Pr[N(t) = n]$, is given by

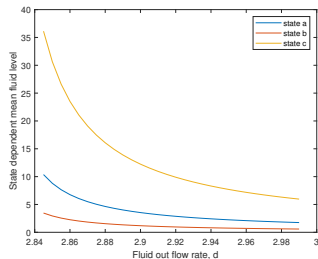
$$\mathbf{p} = \frac{1}{c} \mathbf{m}^{-1} \left[\mathbf{0} \quad \mathbf{I}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \alpha \quad \mathbf{0} \quad \mathbf{0} \right] (-\mathbf{K})^{-1} \left[\mathbf{I}_{|\Theta^+|} \quad \Psi \right] |\mathbf{C}|^{-1}$$
$$\mathbf{P} \left[\frac{\left[\mathbf{0}_{|S_{\varphi(t)}^-| \cdot N \cdot n_{PH}} \right] \left[\mathbf{e}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_N \otimes \mathbf{e}_{n_{PH}} \right]}{\left[\mathbf{e}_{|S_{\varphi(t)}^-|} \otimes \mathbf{I}_{N+1} \right]} \right].$$



Numerical example



(a) Mean fluid level as the function of fluid outflow rate



(b) state dependent mean fluid level as a function of fluid outflow rate

Figure: Mean fluid level versus fluid consumption rate

Here we assume PH distributed vacation time with representation (α, \mathbf{A}) where $\alpha = (0.2, 0.8)$ and $\mathbf{A} = \begin{bmatrix} -2 & 1 \\ 0 & -3 \end{bmatrix}$.



$$\text{Let } \mathcal{S}_{\varphi(t)} = \{a, b, c\}, \mathbf{Q}_{\varphi(t)} = \begin{bmatrix} -8 & 4 & 4 \\ 3 & -12 & 9 \\ 2 & 0 & -2 \end{bmatrix}, \mathbf{R}_{\varphi(t)} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

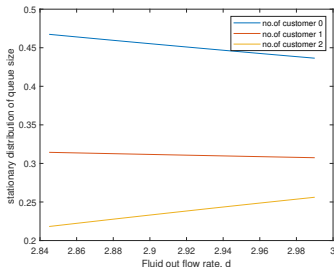


Figure: Stationary queue size distribution versus fluid consumption rate

From these model parameters we have

$\sigma = E(\tilde{\sigma}) = 0.4$, $\pi_{\varphi(t)} = \{0.206897, 0.0689655, 0.724138\}$, and $\lambda_{in} = \bar{\pi}_{\varphi(t)} \mathbf{R}_{\varphi(t)} \mathbf{e} = 1.482758$. Let $\lambda = 2$, $\mu = 3$ and $N = 2$.



When $d > 3$, all effective fluid flow rates are negative (That is, $r_i = c_k - d < 0 \forall i \in \mathcal{S}$) and hence $\mathcal{S}^- = \mathcal{S}_{\varphi(t)} \times \{1, 2\}$, $\mathcal{S}^+ = \mathcal{S}_{\varphi(t)} \times \{0\}$. When $2 < d < 3$, the effective fluid flow rate of state a namely, $3 - d$, is only positive so that $\mathcal{S}^- = \{b, c\} \times \{1, 2\}$ and $\mathcal{S}^+ = (\{a, b, c\} \times (\{0\}, \{a\} \times \{1, 2\}))$. The system is stable when $\rho = \frac{\lambda_{in}}{d_{out}} < 1$, that is when $d_{out} > \lambda_{in} = 1.48276$. When $d = 3$ or $d = 2$, we have a state with zero effective fluid flow rate and the present results are not applicable in these cases. These cases can be addressed only by using an extended model to cover the zero fluid rate case, which is not considered here. Figure 1(a) and Figure 1(b) depict how the overall mean fluid level and the mean fluid level corresponding to each of the background process states are varying with respect to the changes in the values of d . Both these measures are decreasing with the increasing values of d , as expected.



Figure 2 exhibits the variation of stationary queue size distribution $\rho = (p_0, p_1, p_2)$ according to the variation in the values of d . As fluid consumption rate increases, the chance that the fluid level becomes zero is more, which may result in the accumulation of more number of customers in the system. So the probability that the system is empty (p_0) is decreasing and the probability of seeing the system full (p_2) is increasing with increasing values of d , as is clear from Figure 2.



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